

Revisiting AI and Testing Methods to Infer FSM Models of Black-Box Systems

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Global context: inferring models thru testing

- Model-based testing is good (systematic)
 - But often NO model available
- Goal: keep benefits of MBT when no model

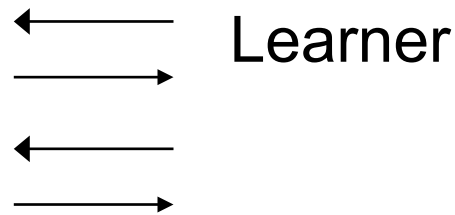
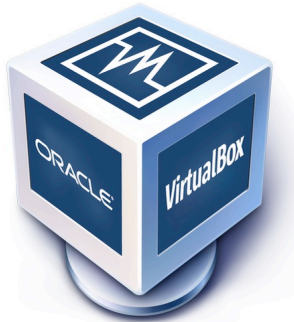
Method: Testing a system is LEARNING the behaviour of a system

→ Use “ML” techniques to learn model

*Problem: learn correct & “complete”
behaviour of Black Box systems
that cannot be reset*

Motivational example

- Reverse-engineer models of Web applications to detect security vulnerabilities using Learning algos (e.g. L^*)
- E-Health app provided by Siemens as a Virtual Machine



- single I/O RTT over LAN: < **1 ms**
- reset=reboot VM: ~**1 minute**

- Timewise: reset is $O(10^5)$ RTT in example
- Many systems CANNOT be reset AT ALL.



Key difficulties when no reset

- How can we know in which state seq is applied ?
- No backtrack possible to check other sequence
- Losing track: we no longer know from where we apply an input

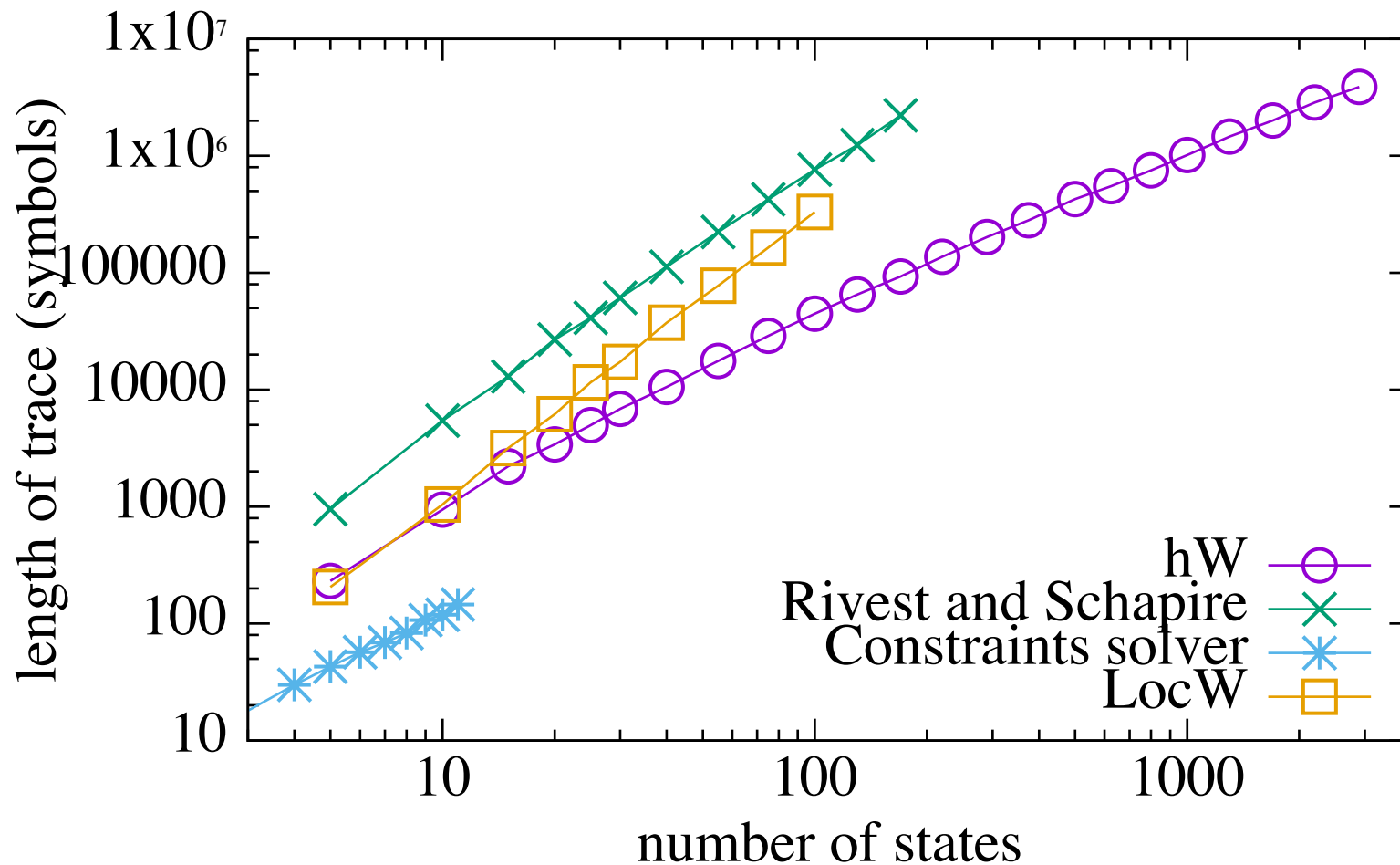


Existing algorithms without reset

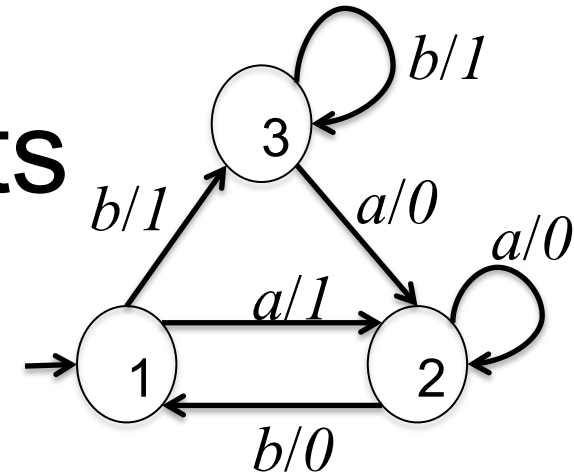
- Rivest & Schapire 1993
 - *Homing sequence*: ersatz for resetting in one of several states
 - Then use a copy of L^* for each homed state
- LocW (Groz & al. 2015)
 - Assume W -set known (*identifying sequences*)
 - Localize in an identifiable state with nested W
- Constraint-solving (Petrenko & al. 2017)
 - Assume bound n on #states.
- NEW (this paper): hW inference
 - *No assumption* ! Discovers h(oming) and W (characterizing)

Results on random machines (log-log)

relationship between length of trace and number of state



Homing seq and W-sets



- $h=a$ is homing sequence:

- After $a/0$ or $a/1$, final state=2,

(in this case h is a reset because single final state)

- $W=\{a,b\}$ is a characterizing set

- $a/1, b/1$: characterize state 1

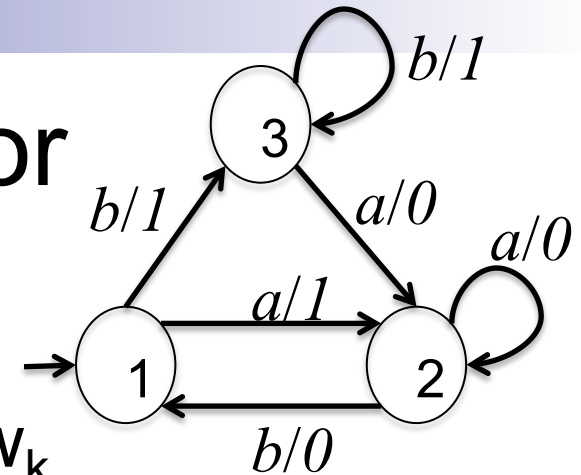
- $a/0, b/0$: characterize state 2

- $a/0, b/1$: characterize state 3

Note: single homing sequence, but most machines require $|W| > 1$

hW inference: core loop for

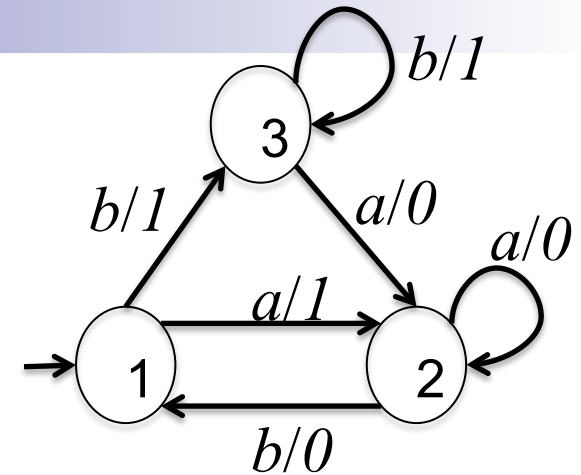
$h=a$ $W=\{a, b\}$



- Repeatedly apply h , an input and w_k to progressively learn transitions
 - More generally $h\alpha w_k$, α transfer seq., x input
- $h/1.w_1/0$ $h/0.w_1/0$ $h/0.w_2/0$
 - At this point we know that tail state of $h/0$ is state characterized by $\{a/0,b/0\}$ (and we are now in state 1)
- $h/1$: we are again in tail state $h/1$, apply w_2
- $b/0$: now we know tail state $h/1$ is $\{a/0,b/0\}$

hW inference: cont'd

$h=a$ $W=\{a, b\}$



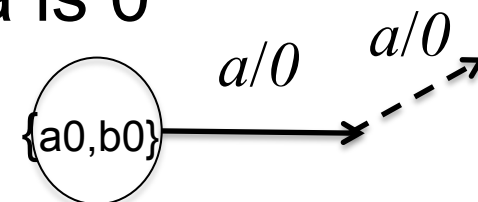
- Known

- $h/0 \rightarrow \{a/0, b/0\}$
- $h/1 \rightarrow \{a/0, b/0\}$

- (and we are in 1). Apply $h: a/1$. We are now in a known state $\{a/0, b/0\}$

- So we learn a transition from it:

- $a/0$ so we know the output on a is 0
- And tail state answers $w_1/0$.



hW inference: cont'd

$h=a$ $W=\{a, b\}$

- Known

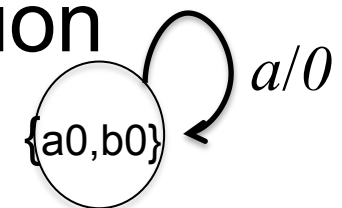
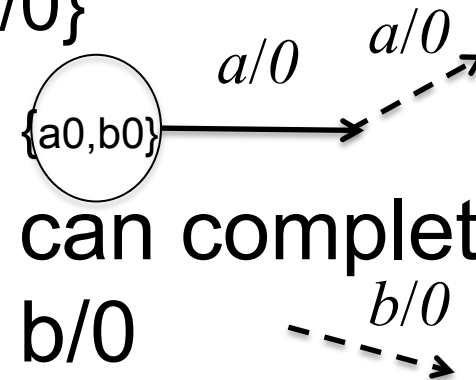
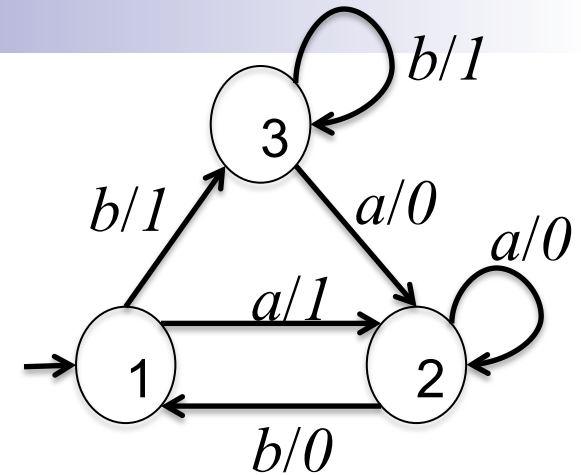
- $h/0 \rightarrow \{a/0, b/0\}$; $h/1 \rightarrow \{a/0, b/0\}$


- Partial transition

- We reapply $h/0$. So now we can complete knowledge of transition: $a/0$ $b/0$

- So we have completely learnt transition

- Going on, we learn the full FSM





Learning with unknown h , W

Key idea: use putative h , W

- Start with any (incorrect) h and W
 - E.g. empty sequence and set
 - Different states will be confused (merged)
 - So this will lead to apparent NonDeterminism (ND)
- ND: reapplying a transition $x/0$, we see $x/1$
 - Depending on context, we can either extend h to hx or W to $W \cup \{x\}$
- Progressively extending h and W until they are homing & characterizing for the BB



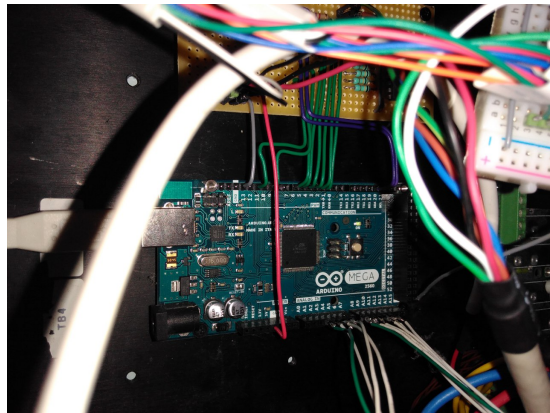
Does it work ?

- Yes !

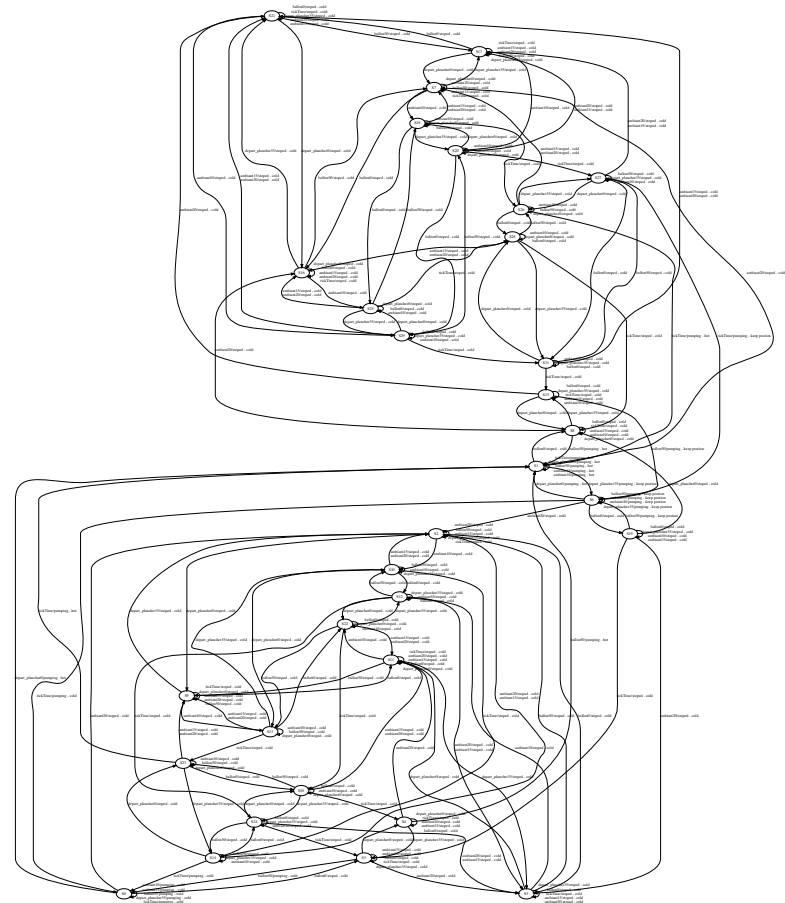
- Naive, but turns out to converge fast
 - Actually, enhanced with a number of heuristics not detailed here
- Outperforms previous algorithms
 - And even algorithms with reset, such as L^*
- No initial knowledge needed (apart input set)
- Still needs an oracle to check equivalence in the end (or get counterexample to refine)
 - Oracle can just be random walk

Does it help with s/w testing ?

■ Example: a Heating Mngmt System



- C++ controller
- 3 temperature inputs + timer -> 9 inputs
- Inferred 36 states, in a few minutes





Results on HMS controller

- RQ1: does hW yield usable models on real CPS ? Yes
- RQ2: testing efficiency / random testing
 - 54 mutations
 - 10 crashes without inputs (hW = RT)
 - 4 killed during inference – also by RT
 - but RT requires many more inputs to kill
 - 35 model inferred: exposes mutation
 - 5 equivalent models (w.r.t. input abstraction)



Conclusion

- New approach to learn FSM models of s/w components without reset
- Full black box, no assumption
- Works surprisingly well, scales up to 1000s states
- Also provides very systematic way of testing reactive software



Perspectives

- Potential breakthrough in Learning Based Testing
 - Resetting a system is a superfluous luxury
 - hW is fast, scaling, does not require any knowledge
- Check applicability on other types of s/w
- Extension to EFSM (data inference)



Thank you !

- Following: backup slides

Inferring model of Black Box

Testing as a means of reverse-engineering a model of a BB



- Classical active inference algorithms assume BB machine can be reset
 - Essential to merge traces (scenarios) on a common basis
- Assume an oracle can provide counterexamples (CE)
 - Essential to bring complexity down to polynomial in #states
 - Example: L^* (Angluin). Complexity is $O(\#inputs \cdot CE_length \cdot \#states^2) = O(fmn^2)$ queries (test seq.)
 - So $O(fmn^2)$ resets